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Second-Order Cone Program (SOCP) Detection and Transformation Algorithms for Optimization Software

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Northwestern University
INFORMS Annual Meeting, Austin, TX

November 8, 2010

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Second-Order Cone Programs (SOCPs)

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- Can be written as a quadratic program
- Not positive semi-definite
- Convex
- Efficiently solvable with interior-point methods

SOCP general form:

$$\text{minimize } f^T x$$

$$\text{subject to } \|A_i x + b_i\|^2 \leq (c_i^T x + d_i)^2 \quad \forall i$$

$$c_i^T x + d_i \geq 0 \quad \forall i$$

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Previous situation:

- SOCPs can be written in numerous equivalent forms
- The form a modeler wants to use may not be the form a solver accepts
- Converting the problem for a particular interior-point solver is tedious and error-prone

Ideal situation:

- Write in modeler's form in a general modeling language
- Automatically transform to a standard quadratic formulation
- Transform as necessary for each SOCP solver

Motivating Example

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$$\text{minimize } \sqrt{(x+2)^2 + (y+1)^2} + \sqrt{(x+y)^2}$$

AMPL model:

```
var x;  
var y;  
minimize objective:  
        sqrt((x+2)^2+(y+1)^2)+sqrt((x+y)^2);
```

CPLEX 12.2.0.0: at2372.nl contains a nonlinear objective.

KNITRO 6.0.0: Current feasible solution estimate cannot be improved.

objective 2.12251253;

30 iterations; 209 function evaluations

Motivating Example

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Original:

$$\text{minimize } \sqrt{(x+2)^2 + (y+1)^2} + \sqrt{(x+y)^2}$$

Transformed:

$$\text{minimize } u + v$$

$$(x+2)^2 + (y+1)^2 \leq u^2$$

$$(x+y)^2 \leq v^2$$

$$u, v \geq 0$$

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Ampl model:

```
var x; var y;  
var u >= 0; var v >= 0;  
minimize obj: u+v;  
s.t. C1: (x+2)^2+(y+1)^2 <= u^2;  
s.t. C2: (x+y)^2 <= v^2;
```

CPLEX 12.2.0.0: QP Hessian is not positive semi-definite.

KNITRO 6.0.0: Locally optimal solution.

objective 2.122027399;

3161 iterations; 3276 function evaluations

Motivating Example

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Original:

$$\text{minimize } \sqrt{(x+2)^2 + (y+1)^2} + \sqrt{(x+y)^2}$$

Transformed:

$$\text{minimize } u + v$$

$$r^2 + s^2 \leq u^2$$

$$t^2 \leq v^2$$

$$x+2 = r$$

$$y+1 = s$$

$$x+y = t$$

$$u, v \geq 0$$

Motivating Example

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Ampl model:

```
var x; var y;  
var u >= 0; var v >= 0;  
var r; var s; var t;  
minimize obj: u+v;  
s.t. C1: r^2+s^2 <= u^2;  
s.t. C2: t^2 <= v^2;  
s.t. C3: x+2 = r;  
s.t. C4: y+1 = s;  
s.t. C5: x+y = t;
```

CPLEX 12.2.0.0: primal optimal; objective 2.121320344

5 barrier iterations

KNITRO 6.0.0: Locally optimal solution.

objective 2.122027305;

3087 iterations; 3088 function evaluations

Generally Accepted SOCP Form

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SOCP general form:

$$\text{minimize } f^T x$$

$$\text{subject to } \|A_i x + b_i\| \leq c_i^T x + d_i \quad \forall i$$

where

- $x \in \mathbb{R}^n$ is the variable
- $f \in \mathbb{R}^n$
- $A_i \in \mathbb{R}^{m_i, n}$
- $b_i \in \mathbb{R}^{m_i}$
- $c_i \in \mathbb{R}^n$
- $d_i \in \mathbb{R}$

Standard Quadratic Form

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Objective: $a_1x_1 + \cdots + a_nx_n$

Constraints:

Quadratic Cone: $b_1x_1^2 + \cdots + b_nx_n^2 - b_0x_0^2 \leq 0$

where $b_i \geq 0 \forall i, x_0 \geq 0$

Rotated Quadratic Cone: $c_2x_2^2 + \cdots + c_nx_n^2 - c_1x_0x_1 \leq 0$

where $c_i \geq 0 \forall i, x_0 \geq 0, x_1 \geq 0$

Linear Inequality: $d_0 + d_1x_1 + \cdots + d_nx_n \leq 0$

Linear Equality: $e_0 + e_1x_1 + \cdots + e_nx_n = 0$

Variable: $k_L \leq x$

Detection Example

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$$\text{minimize } \sqrt{(x+2)^2 + (y+1)^2} + \sqrt{(x+y)^2}$$

Ampl model:

```
var x;  
var y;  
minimize objective:  
sqrt((x+2)^2+(y+1)^2)+sqrt((x+y)^2);
```

First Case: Sum and Max of Norms

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Any combination of

- sum,
- max, and
- constant multiple

of norms can be represented as a SOCP.

Sum of Norms

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$$\underset{i=1}{\text{minimize}} \sum^p \|F_i x + g_i\|$$



$$\underset{i=1}{\text{minimize}} \sum^p y_i$$

$$\text{subject to } \sum_{j=1}^{q_i} u_{ij}^2 - y_i^2 \leq 0, \quad i = 1..p$$

$$(F_i x + g_i)_j - u_{ij} = 0, \quad i = 1..p, \quad j = 1..q_i$$

$$y_i \geq 0, \quad i = 1..p$$

Max of Norms

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Conclusion

$$\text{minimize} \max_{i=1..p} \|F_i x + g_i\|$$



$$\text{minimize } y$$

$$\text{subject to } \sum_{j=1}^{q_i} u_{ij}^2 - y^2 \leq 0, \quad i = 1..p$$

$$(F_i x + g_i)_j - u_{ij} = 0, \quad i = 1..p, \quad j = 1..q_i$$

$$y_i \geq 0, \quad i = 1..p$$

Combination

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$$\text{minimize } 4 \max\{3\|F_1x + g_1\| + 2\|F_2x + g_2\|, 7\|F_3x + g_3\|\}$$



$$\text{minimize } 4y$$

$$\text{subject to } 3u_1 + 2u_2 - y \leq 0$$

$$7u_3 - y \leq 0$$

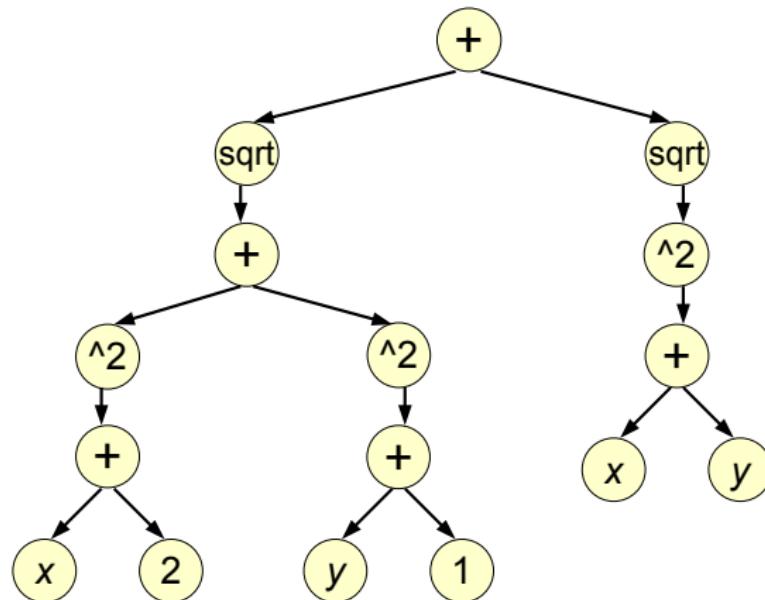
$$\sum_{j=1}^{q_i} v_{ij}^2 - u_i^2 \leq 0, \quad i = 1, 2, 3$$

$$(F_i x + g_i)_j - v_{ij} = 0, \quad i = 1, 2, 3, \quad j = 1..q_i$$

$$u_i \geq 0, \quad i = 1, 2, 3$$

Expression Tree Example

$$\sqrt{(x + 2)^2 + (y + 1)^2} + \sqrt{(x + y)^2}$$



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Sum and Max of Norms (SMN) Detection Function

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Detection Rules for SMN:

Constant: $f(x) = c$ is SMN.

Variable: $f(x) = x_i$ is SMN.

Sum: $f(x) = \sum_{i=1}^n f_i(x)$ is SMN if all the children f_i are SMN.

Product: $f(x) = cg(x)$ is SMN if c is a positive constant and g is SMN.

Maximum: $f(x) = \max\{f_1(x), \dots, f_n(x)\}$ is SMN if all the children f_i are SMN.

Square Root: $f(x) = \sqrt{g(x)}$ is SMN if g is NS.

Norm Squared (NS) Detection Function

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Detection Rules for NS:

Constant: $f(x) = c$ is NS if $c \geq 0$.

Sum: $f(x) = \sum_{i=1}^n f_i(x)$ is NS if all the children f_i are NS.

Product: $f(x) = cg(x)$ is NS if c is a positive constant and g is NS.

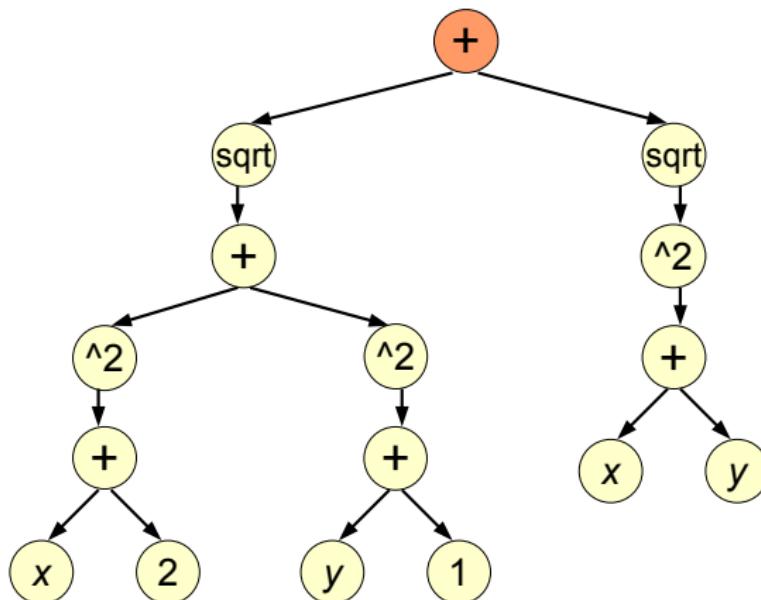
Squared: $f(x) = g(x)^2$ is NS if g is linear.

Maximum: $f(x) = \max\{f_1(x), \dots, f_n(x)\}$ is NS if all the children f_i are NS.

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Sum: $f(x) = \sum_{i=1}^n f_i(x)$ is SMN if all the children f_i are SMN.



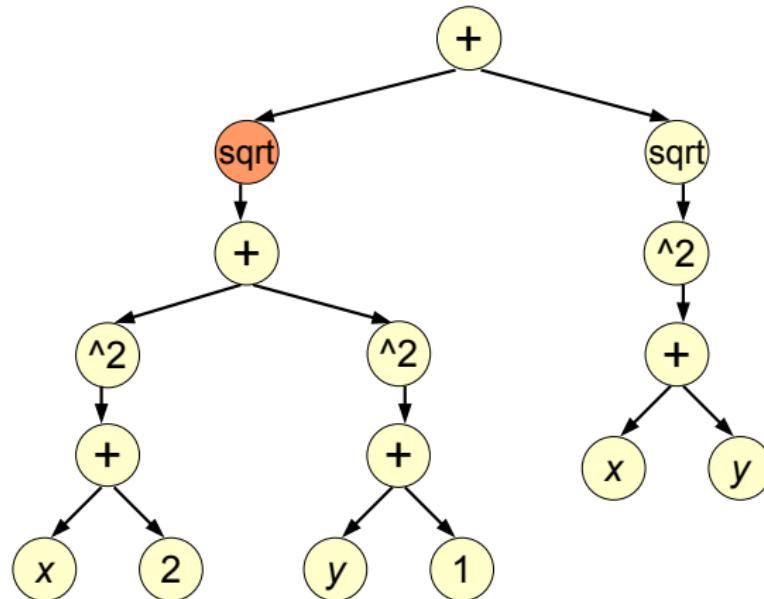
Detection Example

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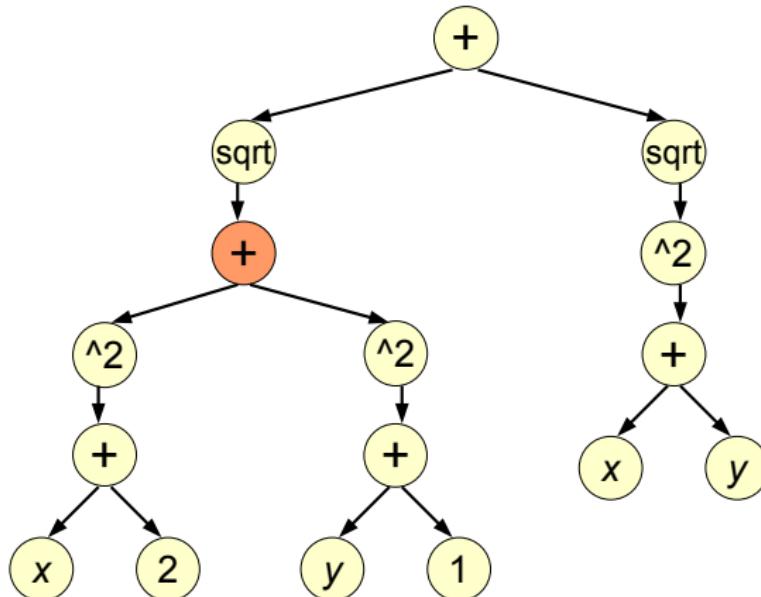
Square Root: $f(x) = \sqrt{g(x)}$ is SMN if $g(x)$ is NS.



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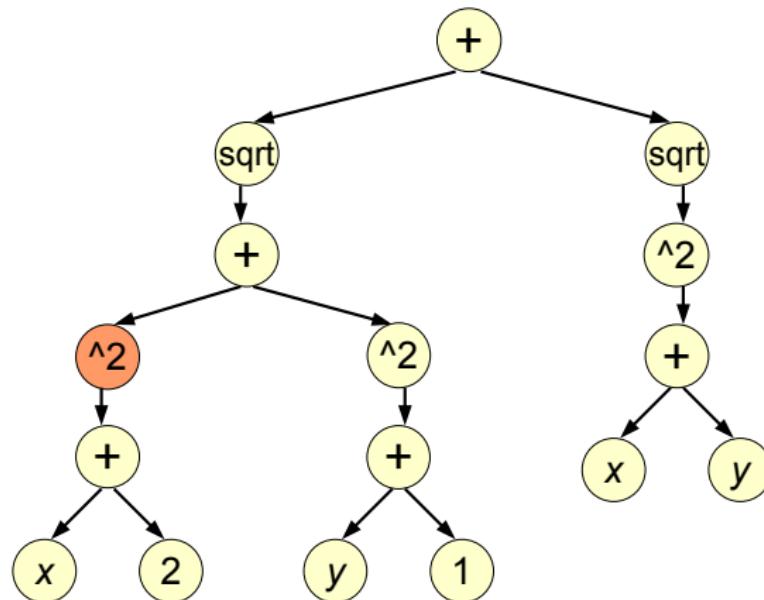
Sum: $f(x) = \sum_{i=1}^n f_i(x)$ is NS if all the children f_i are NS.



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Squared: $f(x) = g(x)^2$ is NS if g is linear.



Transformation Process

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- 1) Determine objective or constraint type with detection rules
- 2) Apply corresponding transformation algorithm
 - Separate algorithm, starts at root
 - Uses no information from detection
 - Creates new variables and constraints
 - New constraints are formed by adding terms to functions

Transformation Conventions

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x : vector of variables in the original formulation

v : vector of variables in the original formulation and variables created during transformation

$f(x), g(x), h(x)$: functions from the original formulation

Functions created during transformation:

$o(v)$: objectives (linear)

$\ell(v)$: linear inequalities

$e(v)$: linear equalities

$q(v)$: quadratic cones

$r(v)$: rotated quadratic cones

$c(v)$: expressions that could fit in multiple categories

Constraint Building Example

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$$\text{Step 1: } \ell_1(v) := 3x_1 + 2$$

$$\text{Step 2: } \ell_1(v) := \ell_1(v) + v_3$$

$$\text{Step 3: } \ell_1(v) \leq 0$$

$$\text{Result: } 3x_1 + 2 + v_3 \leq 0$$

Transformation Functions

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newvar(b)

$n++$

Introduce new variable v_n to variable vector v

if b is specified

 Set lower bound of v_n to b

else

 Set lower bound of v_n to $-\infty$

newfunc(c)

m_c++

Introduce new objective or constraint function of type c

$c_{m_c}(v) := 0$

transformSMN

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transformSMN($f(x)$, $c(v)$, k)

switch

case $f(x) = g(x) + h(x)$

 transformSMN($g(x)$, $c(v)$, k)

 transformSMN($h(x)$, $c(v)$, k)

case $f(x) = \sum_i f_i(x)$

 transformSMN($f_i(x)$, $c(v)$, k) $\forall i$

case $f(x) = \alpha g(x)$

 transformSMN($g(x)$, $c(v)$, $k\alpha$)

transformSMN

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```
case  $f(x) = \max_i f_i(x)$ 
    newvar()
     $c(v) := c(v) + kv_n$ 
    newfunc( $\ell$ ):  $\ell_{m_\ell}(v) := -v_n$ 
    for  $i \in I$ 
        transformSMN( $f_i(x), \ell_{m_\ell}(v), 1$ )
case  $f(x) = \sqrt{g(x)}$ 
    newvar(0)
     $c(v) := c(v) + kv_n$ 
    newfunc( $q$ ):  $q_{m_q}(v) := -v_n^2$ 
    transformNS( $g(x), q_{m_q}(v), 1$ )
```

transformNS

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$\text{transformNS}(f(x), q(v), k)$

switch

case $f(x) = g(x) + h(x)$

$\text{transformNS}(g(x), c(v), k)$

$\text{transformNS}(h(x), c(v), k)$

case $f(x) = \sum_i f_i(x)$

$\text{transformNS}(f_i(x), c(v), k) \forall i$

case $f(x) = \alpha g(x)$

$\text{transformNS}(g(x), c(v), k\alpha)$

transformNS

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```
case  $f(x) = g(x)^2$ 
    newvar()
     $q(v) := q(v) + kv_n^2$ 
    newfunc( $e$ ):  $e_{m_e}(v) := g(x) - v_n$ 
case  $f(x) = \max_i f_i(x)$ 
    newvar()
     $q(v) := q(v) + kv_n^2$ 
    for  $i \in I$ 
        newfunc( $q$ ):  $q_{m_q}(v) := -v_n^2$ 
        transformNS( $f_i(x), q_{m_q}(v), 1$ )
```

Transformation Example

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$$f(x) = \sqrt{(x + 2)^2 + (y + 1)^2} + \sqrt{(x + y)^2}$$

$f(x)$ is SMN \Rightarrow apply corresponding transformation algorithm

Set all index variables to 0

$$o(v) := 0$$

transformSMN($f(x)$, $o(v)$, 1)

Transformation Example

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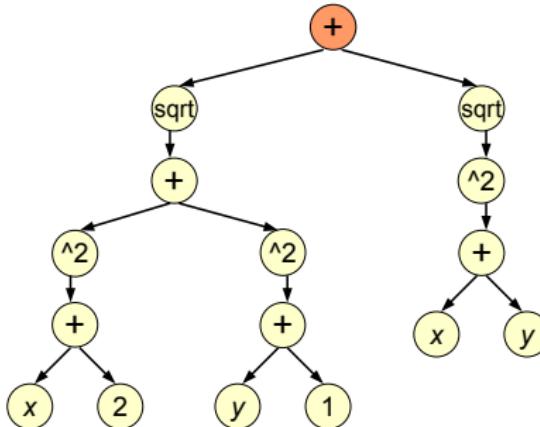
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$$f(x) = \sqrt{(x + 2)^2 + (y + 1)^2} + \sqrt{(x + y)^2}$$

case $f(x) = g(x) + h(x)$

transformSMN($g(x)$, $o(v)$, 1)

transformSMN($h(x)$, $o(v)$, 1)



Transformation Example

$$f(x) = \sqrt{(x + 2)^2 + (y + 1)^2}$$

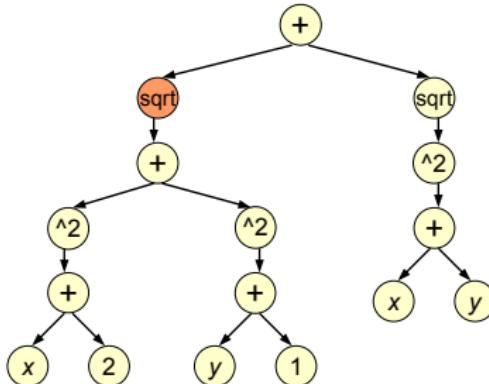
case $f(x) = \sqrt{g(x)}$

newvar(0)

$o(v) := o(v) + v_1$

newfunc(q): $q_1(v) := -v_1^2$

transformNS($g(x)$, $q_1(v)$, 1)



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Transformation Example

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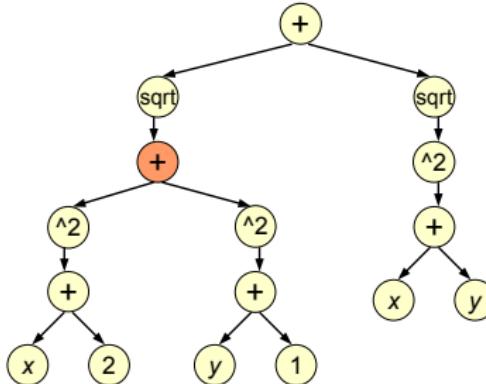
Conclusion

$$f(x) = (x + 2)^2 + (y + 1)^2$$

case $f(x) = g(x) + h(x)$

transformNS($g(x)$, $q_1(v)$, k)

transformNS($h(x)$, $q_1(v)$, k)



Transformation Example

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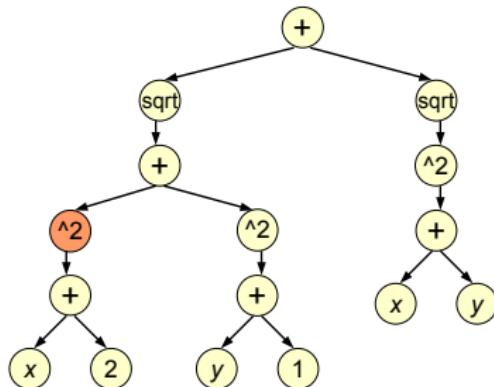
$$f(x) = (x + 2)^2$$

case $f(x) = g(x)^2$

newvar()

$q_1(v) := q_1(v) + v_2^2$

newfunc(e): $e_1(v) := g(x) - v_2$



Current Functions

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$$o(v) = v_1$$

$$q_1(v) = v_2^2 - v_1^2$$

$$e_1(v) = x + 2 - v_2$$

$$v_1 \geq 0$$

Final Functions

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$$o(v) = v_1 + v_4$$

$$q_1(v) = v_2^2 + v_3^2 - v_1^2 \leq 0$$

$$e_1(v) = x + 2 - v_2 = 0$$

$$e_2(v) = y + 1 - v_3 = 0$$

$$q_2(v) = v_5^2 - v_4^2 \leq 0$$

$$e_3(v) = x + y - v_5 = 0$$

$$v_1 \geq 0$$

$$v_4 \geq 0$$

Motivating Example

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Original:

$$\text{minimize } \sqrt{(x+2)^2 + (y+1)^2} + \sqrt{(x+y)^2}$$

Transformed:

$$\text{minimize } u + v$$

$$r^2 + s^2 \leq u^2$$

$$t^2 \leq v^2$$

$$x+2 = r$$

$$y+1 = s$$

$$x+y = t$$

$$u, v \geq 0$$

Other Objective Forms

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- Norm Squared:

$$\underset{i=1}{\text{minimize}} \sum_{i=1}^p c_i(a_i x + b_i)^2$$

- Fractional:

$$\underset{i=1}{\text{minimize}} \sum_{i=1}^p \frac{c_i \|F_i x + g_i\|^2}{a_i x + b_i}$$

where $a_i x + b_i > 0 \forall i$

- Logarithmic Chebyshev:

$$\underset{i=1..p}{\text{minimize}} \max | \log(a_i x) - \log(b_i) |$$

where $a_i x > 0$

Other Objective Forms

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- Product of Positive Powers:

$$\text{maximize} \prod_{i=1}^p (a_i x + b_i)^{\alpha_i}$$

where $\alpha_i > 0$, $\alpha_i \in \mathbb{Q}$, $a_i x + b_i \geq 0$

- Product of Negative Powers:

$$\text{minimize} \prod_{i=1}^p (a_i x + b_i)^{-\pi_i}$$

where $\pi_i > 0$, $\pi_i \in \mathbb{Q}$, $a_i x + b_i \geq 0$

- Combinations of these forms made by sum, max, and positive constant multiple, except Log Chebyshev and some cases of Product of Positive Powers. Example:

$$\text{minimize} \max \left\{ \sum_{i=1}^p (a_i x + b_i)^2, \sum_{j=1}^q \frac{\|F_j x + g_j\|^2}{y_j} \right\} + \prod_{k=1}^r (c_k x)^{-\pi_k}$$

Constraint Forms

- Sum and Max of Norms:

$$\sum_{i=1}^p c_i \|F_i x + g_i\| \leq ax + b$$

- Norm Squared:

$$\sum_{i=1}^p c_i (a_i x + b_i)^2 \leq c_0 (a_0 x + b_0)^2$$

where $c_0 \geq 0$, $a_0 x + b_0 \geq 0$

- Fractional:

$$\sum_{i=1}^p \frac{k_i \|F_i x + g_i\|^2}{a_i x + b_i} \leq cx + d$$

where $a_i x + b_i > 0 \forall i$

Constraint Forms

- Product of Positive Powers:

$$\sum_j - \prod_i (a_{ji}x + b_{ji})^{\pi_{ji}} \leq cx + d$$

where $a_{ji}x + b_{ji} \geq 0$, $\pi_{ji} > 0$, $\sum_i \pi_{ji} \leq 1 \forall j$

- Product of Negative Powers:

$$\sum_j \prod_i (a_{ji}x + b_{ji})^{-\pi_{ji}} \leq cx + d$$

where $a_{ji}x + b_{ji} \geq 0$, $\pi_{ji} > 0$

- Combinations of these forms made by sum, max, and positive constant multiple

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- Implementation for AMPL and several solvers
- Paper documenting algorithms
- Extend to functions not included in AMPL

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Thank You

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This work was supported in part by grant CMMI-0800662 from the National Science Foundation.