New Connections to the AMPL Modeling Language: Spreadsheets and Callbacks

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New Connections to the AMPL Modeling Language: Spreadsheets and Callbacks

Optimization applications are often concerned as much with making connections as with building models. This presentation describes two connections recently implemented in the AMPL modeling language and system. A direct spreadsheet connection reads and writes xlsxformat files, defining correspondences between common spreadsheet layouts and AMPL's algebraic data definitions. Support is included for "twodimensional" spreadsheet tables in

which one index labels the columns and one or more indices label the rows. A solver callback connection enables AMPL's APIs to communicate with algorithms as they are running, uniting the ease of modeling in AMPL with the flexibility of programming to customize algorithmic behavior. This facility can be used to write specialized routines that report progress, change settings, and generate constraints that cut off fractional solutions.

Outline

Direct interface to spreadsheet files

- ❖ Implementation as a new AMPL data-table handler
- **Example:** Multicommodity network flow

Callbacks from solvers

- ❖ Implementation in AMPL APIs for Python, C++, C#
 - **★** Python in Jupyter notebooks with AMPL cells
- Example: Custom solver stopping criterion
 - * Optimal pattern selection for roll cutting
- * Example: Generation of subtour elimination cuts
 - * Minimum tour (TSP) in a network

Read & write any .xlsx file

- Independent of the spreadsheet software used
- Works on all popular platforms (Windows, Linux, macOS)
- Bypasses database drivers such as ODBC

Use existing AMPL data-interface statements

- table for making associations between
 AMPL model parameters and spreadsheet data
- read table and write table for importing and exporting data

Now available . . .

❖ *Direct .csv file handler*

Network Flow (symbolic data)

Given

```
P set of productsN set of network nodes
```

 $A \subseteq N \times N$ set of arcs connecting nodes

and

```
u_{ij} capacity of arc from i to j, for each (i,j) \in A
```

```
s_{pj} supply/demand of product p at node j, for each p \in P, j \in N > 0 implies supply, < 0 implies demand
```

```
c_{pij} cost per unit to ship product p on arc (i, j), for each p \in P, (i, j) \in A
```

Network Flow (symbolic model)

Determine

 X_{pij} amount of commodity p to be shipped from node i to node j, for each $p \in P$, $(i, j) \in A$

to minimize

$$\sum_{p \in P} \sum_{(i,j) \in A} c_{pij} X_{pij}$$
total cost of shipping

subject to

$$\sum_{p \in P} X_{pij} \le u_{ij}$$
, for all $(i, j) \in A$

total shipped on each arc must not exceed capacity

$$\sum_{(i,j)\in A} X_{pij} + s_{pj} = \sum_{(j,i)\in A} X_{pji}, \text{ for all } p \in P, j \in N$$

shipments in plus supply/demand must equal shipments out

Network Flow in AMPL

Symbolic data and model

```
set PRODUCTS;
set NODES:
set ARCS within {NODES, NODES};
param capacity {ARCS} >= 0;
param inflow {PRODUCTS, NODES};
param cost {PRODUCTS,ARCS} >= 0;
var Flow {PRODUCTS,ARCS} >= 0:
minimize TotalCost:
   sum {p in PRODUCTS, (i,j) in ARCS} cost[p,i,j] * Flow[p,i,j];
subject to Capacity {(i,j) in ARCS}:
   sum {p in PRODUCTS} Flow[p,i,j] <= capacity[i,j];</pre>
subject to Conservation {p in PRODUCTS, j in NODES}:
   sum \{(i,j) \text{ in ARCS}\}\ Flow[p,i,j] + inflow[p,j] =
   sum {(j,i) in ARCS} Flow[p,j,i];
```

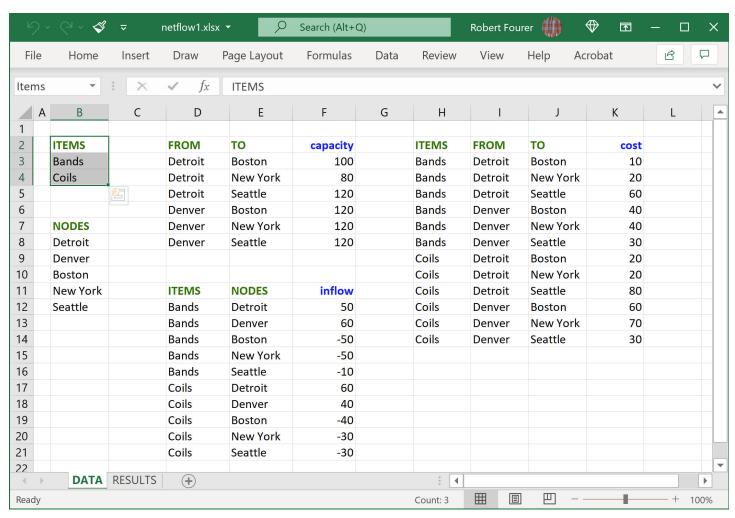
Data Instance

in AMPL text format

```
set PRODUCTS := Bands Coils ;
set NODES := Detroit Denver Boston 'New York' Seattle ;
param: ARCS: capacity:
       Boston 'New York' Seattle :=
Detroit
          100
                  80
                          120
          120 120
Denver
                          120 ;
param inflow:
        Detroit Denver Boston 'New York' Seattle :=
 Bands
           50
                 60
                        -50
                               -50
                                        -10
 Coils
           60
                 40 -40 -30
                                        -30;
param cost:
 [Bands,*,*] Boston 'New York' Seattle :=
    Detroit
                                60
               10
                        20
    Denver
               40
                        40
                                30
 [Coils,*,*] Boston 'New York' Seattle :=
    Detroit
              20
                        20
                                80
               60
    Denver
                        70
                                30 ;
```

Data Instance

in spreadsheet ranges



Data Handling

Script file (input)

```
model netflow1.mod;
table Products IN "amplx1" "netflow1.xlsx" "Items":
    PRODUCTS <- [ITEMS];
table Nodes IN "amplx1" "netflow1.xlsx":
    NODES <- [NODES];
table Capacity IN "amplx1" "netflow1.xlsx":
    ARCS <- [FROM, TO], capacity;
table Inflow IN "amplx1" "netflow1.xlsx":
    [ITEMS, NODES], inflow;
table Cost IN "amplxl" "netflow1.xlsx":
    [ITEMS, FROM, TO], cost;
load amplx1.dll;
read table Products; read table Nodes;
read table Capacity; read table Inflow; read table Cost;
```

Data Handling

Script file (output)

```
option solver gurobi;
solve;

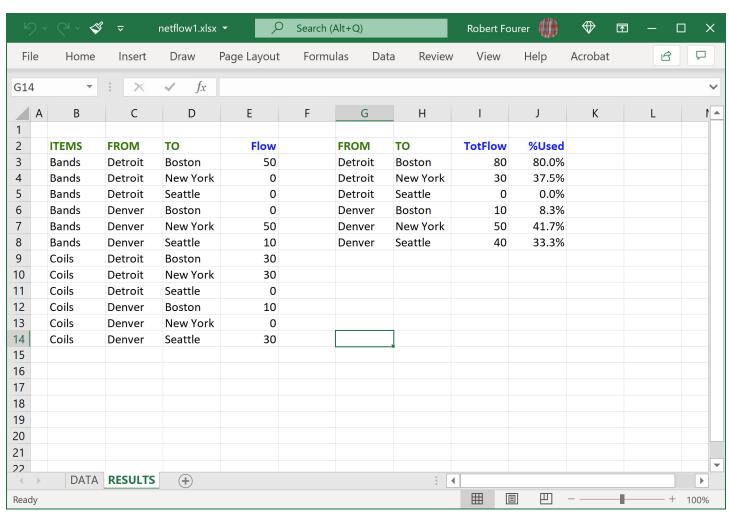
table Results OUT "amplxl" "netflow1.xlsx":
    [ITEMS,FROM,TO], Flow;

table Summary OUT "amplxl" "netflow1.xlsx":
    {(i,j) in ARCS} -> [FROM,TO],
    sum {p in PRODUCTS} Flow[p,i,j] ~ TotFlow,
    sum {p in PRODUCTS} Flow[p,i,j] / capacity[i,j] ~ "%Used";

write table Results;
write table Summary;
```

Data Results

in spreadsheet ranges



And There's More...

All existing features supported

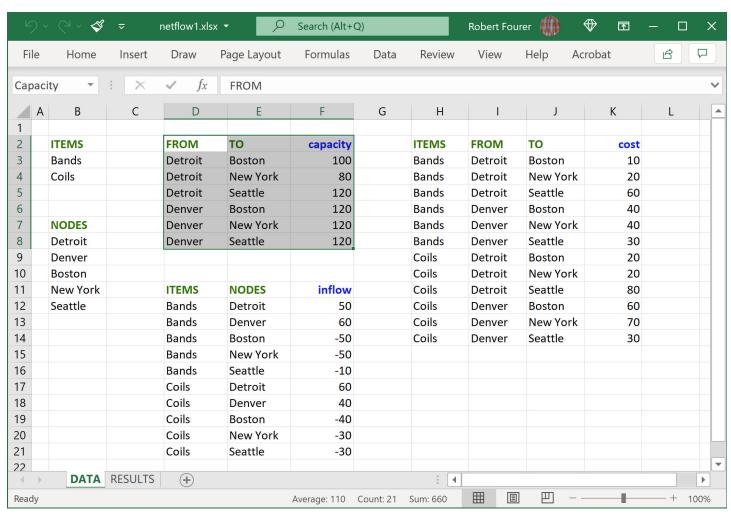
- Indexed collections of tables
- Dynamic file, range & header names in tables
- * read table, write table in loops and conditionals

New spreadsheet-specific features

- Recognize both sheet and range names
- Properly interpret empty data cells
- Handle "two-dimensional" spreadsheet tables

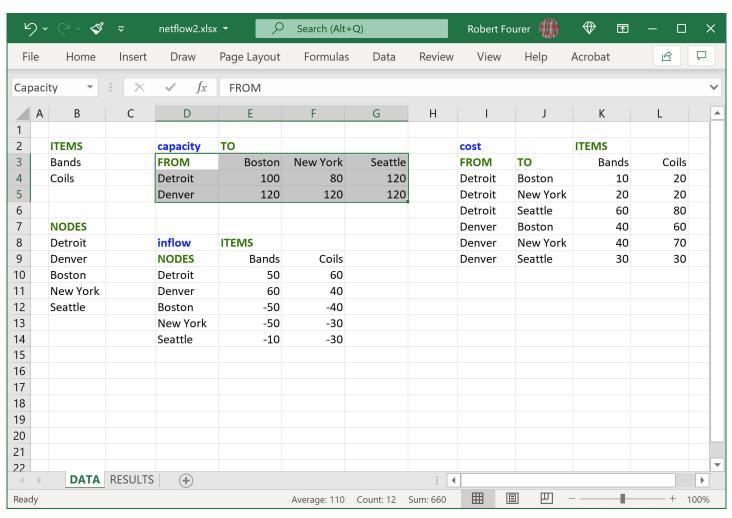
Data Instance (revisited)

"1D" spreadsheet ranges



Data Instance (revisited)

"2D" spreadsheet ranges



Data Handling (revisited)

Script file (input)

```
model netflow1.mod;
table Products IN "amplx1" "netflow2.xlsx" "Items":
    PRODUCTS <- [ITEMS];
table Nodes IN "amplx1" "netflow2.xlsx":
    NODES <- [NODES];
table Capacity IN "amplx1" "netflow2.xlsx" "2D":
    ARCS <- [FROM, TO], capacity;
table Inflow IN "amplx1" "netflow2.xlsx" "2D":
    [ITEMS, NODES], inflow;
table Cost IN "amplxl" "netflow2.xlsx" "2D":
    [ITEMS, FROM, TO], cost;
load amplx1.dll;
read table Products; read table Nodes;
read table Capacity; read table Inflow; read table Cost;
```

Data Handling

Script file (output)

```
option solver gurobi;
solve;

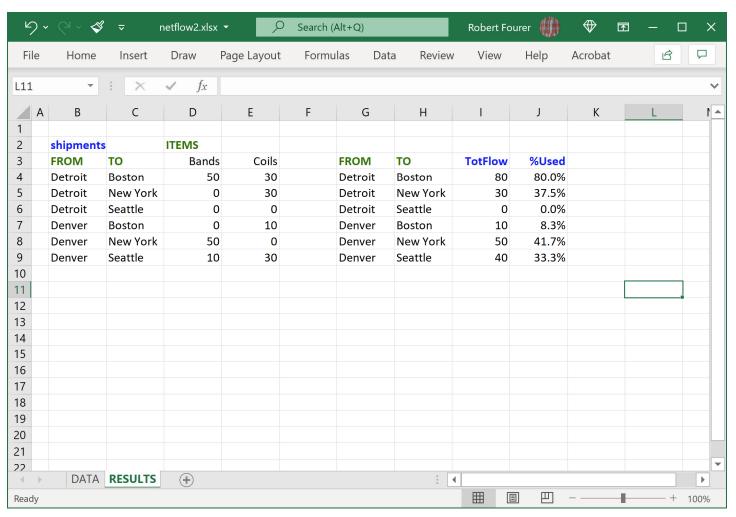
table Results OUT "amplxl" "netflow1.xlsx" "2D":
    [ITEMS,FROM,TO], Flow;

table Summary OUT "amplxl" "netflow1.xlsx":
    {(i,j) in ARCS} -> [FROM,TO],
    sum {p in PRODUCTS} Flow[p,i,j] ~ TotFlow,
    sum {p in PRODUCTS} Flow[p,i,j] / capacity[i,j] ~ "%Used";

write table Results;
write table Summary;
```

Data Results

"2D" spreadsheet ranges



Callbacks from Solvers

Generic implementation in AMPL APIs

- ❖ In multiple languages: Python, C++, C#
- ❖ For multiple solvers: CPLEX, Gurobi, Xpress
 - * based on our AMPL-enabled distribution
- ❖ With multiple *generic* callback types: MIPNODE, MIPSOL, . . .
 - * Solver specific callbacks also available

Sample uses

- Implementing a solver stopping criterion
 - * optimal pattern selection for roll cutting
- Adding user-generated constraints
 - * minimum tour (TSP) of a network

Examples in Python

Jupyter notebooks with AMPL cells

Callbacks from Solvers

Pattern Selection for Roll Cutting

Given

- * Raw rolls of a large (fixed) width
- Demands for various (smaller) ordered widths
- Selected cutting patterns that may be used

Determine

Number of times to cut each pattern

So that

- Demands are met (or slightly exceeded)
- ❖ Number of raw rolls cut is minimized

Roll Cutting

Solution Strategy

Generate many "good" cutting patterns

Example: solve knapsack subproblems

Solve integer program using all patterns generated

- ❖ Apply a solver for a "reasonable" amount of time
- * Return the best (possibly optimal) solution found

... using a callback to implement an adaptive stopping rule

Callbacks from Solvers

Stopping Rule

Data

- ❖ Times $t_1 < t_2 < t_3$ etc.
- ❖ Optimality gap tolerances $g_1 < g_2 < g_3$ etc.

Execution

- \diamond When elapsed time reaches $t_i \dots$
- \diamond Increase the gap tolerance to g_i

Stopping Rule

Implementation Highlights

Stopping rule data in Python dictionary

Callback class (constructor)

```
class MyCallback(ampls.GenericCallback):
    def __init__(self, stoprule):
        super(MyCallback, self).__init__()
        self._stoprule = stoprule
        self._current = 0
        self._continueOpt = True
    ......
```

Stopping Rule

Implementation Highlights

Callback class (process callback, update gap tolerance)

```
def run(self):
    where = self.getAMPLWhere()
    if where == ampls.Where.MIPNODE:
        runtime = self.getValue(ampls.Value.RUNTIME).dbl
        if runtime >= self._stoprule['time'][self._current]:
            self._continueOpt = True
            return -1
    return 0
def setCurrentGap(self):
    gaptolpct = 100*self._stoprule['gaptol'][self._current]
    stoptime = self._stoprule['time'][self._current]
    print("Increasing gap tolerance to "
          f"{gaptolpct:.2f}% after {stoptime:.1f} seconds")
    ampls_model.setAMPLsParameter(ampls.SolverParams.DBL_MIPGap,
                         self._stoprule['gaptol'][self._current])
    self. current += 1
```

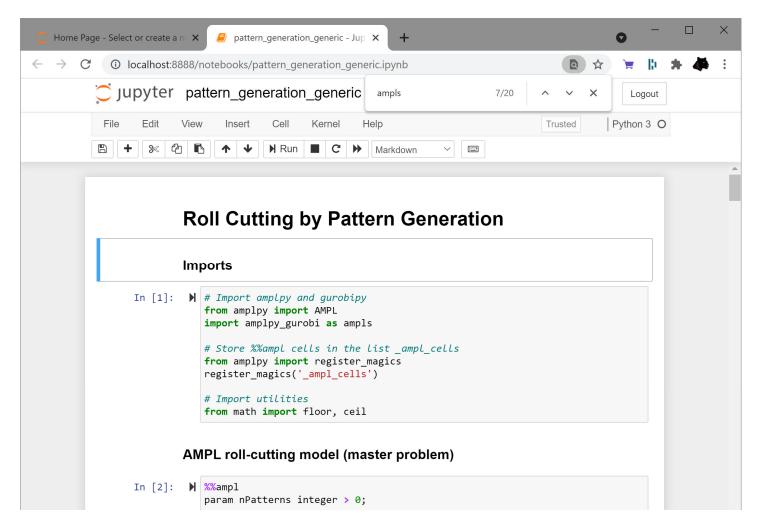
Stopping Rule

Implementation Highlights

Solve using callbacks

```
# Export
Master.option['relax_integrality'] = 0
ampls_model = Master.exportModel(solver, ["return_mipgap=5"])
# Initialize with stopping rule
callback = MyCallback(stopdict)
ampls_model.setCallback(callback)
# Invoke solver
while callback._continueOpt:
    callback._continueOpt = False
    ampls_model.optimize()
    if callback._continueOpt:
        callback.setCurrentGap()
# Import solution from solver
Master.importSolution(ampls_model)
```

Roll-Cutting Notebook



https://ampl.com/dl/Notebooks/patgen_callback.zip

Callbacks from Solvers

Minimum Tour (TSP)

Given

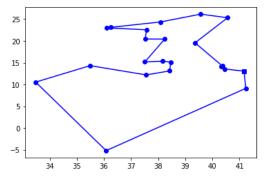
- ❖ A set of locations ("nodes")
- Distances between pairs of locations ("arcs")

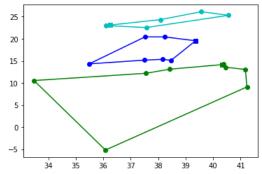
Choose

❖ A subset of arcs having minimum total distance

So that

- Exactly two arcs meet each node (adjacency)
- * At least two arcs connect every subset of nodes to the other nodes (*subtour elimination*)





Solution Strategy

Start with only adjacency constraints For each feasible solution found,

- Check for subtours
- * Add an elimination constraint for each subtour found
- Continue with the optimization

... using a callback to add the elimination constraints

Implementation Highlights

Set a few execution parameters

```
solver = "cplex"
tspFile = "TSP/ch150.tsp"
PLOTSUBTOURS = True
```

Read TSPLIB file into a dictionary

```
def getDictFromTspFile(tspFile):
    p = tsp.load(tspFile)
    nnodes = len(list(p.get_nodes()))
    formatString = f"{{:0{ceil(log10(nnodes+1))}}d}}"
    nodes = {formatString.format(value) : p.node_coords[index+1]
        for index, value in enumerate(p.get_nodes())}
    return nodes
```

Implementation Highlights

Create AMPL object, load model and data

```
# Create AMPL object and set solver
ampl = AMPL()
ampl.option["solver"] = solver
# Load model in AMPL
tspAMPLModel = _ampl_cells[0]
ampl.eval(tspAMPLModel)
# Read TSPLIB file and pass data to AMPL
nodes = getDictFromTspFile(tspFile)
df = DataFrame(index=[('NODES')], columns=['hpos', 'vpos'])
df.setValues(nodes)
ampl.setData(df, "NODES")
```

Implementation Highlights

Define callback

```
class MyCallback(ampls.GenericCallback):
    def __init__(self):
     # Constructor, simply sets the iteration number to 0
      super().__init__()
      self.iteration = 0
    def run(self):
     try:
         # For each solution
         if self.getAMPLWhere() == ampls.Where.MIPSOL:
            self.iteration += 1
            print(f"\nIteration {self.iteration}: Finding subtours")
            sol = self.getSolutionVector()
            arcs = [xvars[i] for i,value in enumerate(sol) if value > 0]
            subTours = findSubTours(set(arcs), set(vertices))
            if len(subTours) == 1:
                print("No subtours detected. Not adding any cut")
                return 0
```

Implementation Highlights

Define callback (cont'd)

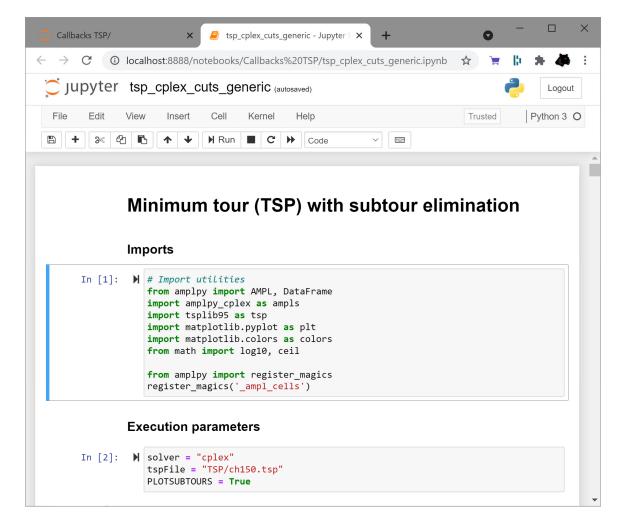
```
class MyCallback(ampls.GenericCallback):
    def run(self):
             for subTour in subTours:
                st1 = set(subTour)
                nst1 = set(vertices) - st1
                externalArcs = [(i,j) if i < j else (j,i)</pre>
                                 for i in st1 for j in nst1]
                varsExternalArcs = [xinverse[(i,j)]
                                     for (i,j) in externalArcs]
                coeffs = [1 for i in range(len(varsExternalArcs))]
                varsExternalArcs = sorted(varsExternalArcs)
                self.addLazyIndices(varsExternalArcs , coeffs,
                                     ampls.CutDirection.GE, 2)
                if len(subTours) == 2:
                   return 0
             print("Continue solving")
          return 0
```

Implementation Highlights

Run subtour elimination

```
# Export the model using ampls
model = ampl.exportModel(solver)
model.enableLazyConstraints()
# Get the global maps between solver vars and AMPL entities
varMap = model.getVarMapFiltered("X")
inverse = model.getVarMapInverse()
xvars = ...
xinverse = ...
vertices = ...
# Assign the callback
callback = MyCallback()
model.setCallback(callback)
# Start the optimization
model.optimize()
# Import the solution back to AMPL
ampl.importSolution(model)
```

Minimum Tour Notebook



https://ampl.com/dl/Notebooks/mintour_callback.zip

Availability

Direct spreadsheet interface

- * implementation by Nicolau Santos
- ❖ Included in all AMPL distributions
- Details at ampl.com/resources/new-features/spreadsheets/

Solver callbacks

- * implementation by Christian Valente, Filipe Brandão
- Available for beta testing
- Write to support@ampl.com for details

